

Lie rackoids

Camille Laurent-Gengoux
Université de Lorraine (Metz)

Friedrich Wagemann
Université de Nantes

November 11, 2015

Abstract

We define a new differential geometric structure, called Lie rackoid. It relates to Leibniz algebroids exactly as Lie groupoids relate to Lie algebroids. Its main ingredient is a selfdistributive product on the manifold of bisections of a smooth precategory.

We show that the tangent algebroid of a Lie rackoid is a Leibniz algebroid and that Lie groupoids gives rise via conjugation to a Lie rackoid. Our main objective are large classes of examples, including a Lie rackoid integrating the Dorfman bracket without the cocycle term of the standard Courant algebroid.

Introduction

There is a growing literature dealing with what is called indifferently Leibniz algebra or Loday algebra, see for example [12], and its infinite dimensional counterpart, namely Leibniz or Loday algebroids, see e.g. [8], [18]. We shall prefer here to use the name Leibniz algebra (following J.-L. Loday), rather than Loday algebra, although Loday is certainly the main promotor of the theory¹. Recall that a Leibniz or Loday algebra is a vector space \mathfrak{h} equipped with a bilinear bracket that satisfies a Jacobi identity (meaning that the left adjoint is a derivation of the bracket) although it is not necessarily skew-symmetric. In an equation:

$$[X, [Y, Z]] = [[X, Y], Z] + [Y, [X, Z]]$$

for all elements $X, Y, Z \in \mathfrak{h}$. A Leibniz algebroid is then a vector bundle on some manifold M together with an anchor map such that the space of sections carries the structure of a Leibniz algebra. A subtlety with the definition of Leibniz algebroid is that we only have, in general, an anchor map for the left adjoint action. Observe that under light conditions a Leibniz bracket which is a derivation in both of its arguments must be antisymmetric, see [7].

Our main goal in this article is to investigate the integrated or group-version of a Leibniz algebroid. We call this new structure *Lie rackoids*, because the tangent space at 1 of a Lie rack is a Leibniz algebra (see [9]) generalizing the

¹The concept of a Leibniz algebra appears in a paper by Blokh in 1965.

tangent Lie algebra of a Lie group. It is therefore natural to call the -oid version Lie rackoid. Our definition of a Lie rackoid draws on the conjugation Lie rackoid underlying a Lie groupoid. Indeed, the set of bisections in a Lie groupoid is a major actor for defining a conjugation in a Lie groupoid. We define, roughly speaking, a Lie rackoid structure as being a selfdistributive operation, i.e. for all x, y, z

$$x \triangleright (y \triangleright z) = (x \triangleright y) \triangleright (x \triangleright z),$$

on the set of bisections of some precategory which also acts on all arrows in the precategory.

It is thus clear that one big class of examples for Lie rackoids are those underlying a Lie groupoid (Proposition 5.1). Another expected result is that the tangent structure of a Lie rackoid is a Leibniz algebroid (Theorem 5.3). More classes of examples are obtained from rackoid structures on those precategories where source map and target map coincide (bundles of Lie racks, see Section 4), or from the augmented rack construction, suitably transposed in the present context (see Section 6.2). Our main example (see Proposition 6.2) is the Lie rackoid integrating the hemisemidirect product Leibniz algebroid made from the action of vector fields on 1-forms with the bracket

$$[X + \alpha, Y + \beta] = [X, Y] + \mathcal{L}_X \beta$$

for all $X, Y \in \mathcal{X}(M), \alpha, \beta \in \Omega^1(M)$. It is clear that this Leibniz algebroid is, up to a cocycle, the Dorfman bracket of the standard Courant algebroid. Our search for the correct definition of a Lie rackoid was largely motivated by the integration of Courant algebroids, which was achieved in the framework of graded geometry in [14], [11], [19], but which we wanted to explore using ordinary differential geometry. Namely, in the graded geometry framework, it is not clear how Dirac structures give rise to Lie subgroupoids of the integrated object. We plan to clarify this using a Lie rackoid integrating the standard Courant algebroid in a follow-up article.

In order to explain our concepts in a down-to-earth manner, we start by explaining the concept of a (plain) rackoid (Definition 2.8), not involving smoothness. Augmented rackoids are taken care of in Section 2.4 - the main construction mechanism for rackoids in our article. Then we pass to Lie rackoids in Section 3. The main idea is to give the set of bisections of a smooth precategory an infinite-dimensional (Fréchet-) manifold structure, inspired by work of Schmeding-Wockel [17]. A Lie rackoid is then a smooth selfdistributive structure on this manifold of bisections (Definition 3.5). The rest of the article discusses the above mentioned structure results and classes of examples.

Acknowledgements: FW thanks Université Lorraine for financing several visits to Metz where this research has been carried out.

1 Bisections in a Lie groupoid

Let $\Gamma \xrightleftharpoons[t]{s} M$ be a groupoid on a base manifold M with source s and target t . Notice that we use composition conventions which are the opposite of those in [13]: our groupoid multiplications are read from left to right. This means in particular that two elements $x, y \in \Gamma$ are compatible (i.e. their product xy is defined) if and only if $t(x) = s(y)$.

For two subsets $X, Y \subset \Gamma$, we shall denote by $X \star Y$ the subset of Γ made of all possible products of elements in X with elements in Y :

$$X \star Y := \{xy, (x, y) \in (\Gamma \times_{t, M, s} \Gamma) \cap (X \times Y)\} \quad (1)$$

The product \star is of course associative:

$$X \star (Y \star Z) = (X \star Y) \star Z$$

for all $X, Y, Z \subset \Gamma$.

In order to express left translation, right translation, and then conjugation on Γ , one is led to the concept of a bisection.

Definition 1.1. Let $\Gamma \xrightleftharpoons[t]{s} M$ be a groupoid over M .

(a) A *bisection* of Γ is any of the two equivalent data:

- (i) a subset $\Sigma \subset \Gamma$ such that (the restrictions of) source and target maps $s : \Sigma \rightarrow M$ and $t : \Sigma \rightarrow M$ are bijective.
- (ii) a map $\sigma : M \rightarrow \Gamma$ which is right inverse to the source map s (i.e. a section of s) and for which $t \circ \sigma : M \rightarrow M$ is a bijection of M .

Bisections seen as subsets shall be in general denoted by capital greek letters and their corresponding maps by the corresponding greek script letters, e.g. Σ and σ , \mathcal{T} and τ .

(b) For a given bisection Σ , the *left translation* induced by Σ is the bijection of Γ given by:

$$l_\Sigma : \Gamma \rightarrow \Gamma, \quad \gamma \mapsto \sigma((t \circ \sigma)^{-1}(s(\gamma))) \quad \gamma = \Sigma \star \{\gamma\}.$$

(c) Similarly, the *right translation* induced by Σ is

$$r_\Sigma : \Gamma \rightarrow \Gamma, \quad \gamma \mapsto \gamma \sigma(t(\gamma)) = \{\gamma\} \star \Sigma.$$

(d) Combining both, the *conjugation* induced by Σ is

$$c_\Sigma : \Gamma \rightarrow \Gamma, \quad \gamma \mapsto \sigma((t \circ \sigma)^{-1}(s(\gamma))) \quad \gamma \tilde{\sigma}(t(\gamma)) = \Sigma \star \{\gamma\} \star \Sigma^{-1},$$

where $\tilde{\sigma}(m) = (\sigma(t \circ \sigma)^{-1}(m))^{-1}$ is the section of s associated to the bisection Σ^{-1} .

For every Lie groupoid Γ , bisections form a group. The group product of bisections Σ, \mathcal{T} , seen as subsets of Γ , is simply given by $\Sigma \star \mathcal{T}$.

Remark 1.2. There is another reason to be interested in bisections which is related to the integration of Lie algebroids. Indeed, given a section $a \in \Gamma(A)$ of a Lie algebroid $A \rightarrow M$, consider the local flow $t \rightarrow \Phi_t^a$ of the left invariant vector field on Γ associated to a . As explained in Appendix A in [4], for t small enough and a compactly supported, the submanifold $\Sigma_t := \Phi_t^a(M)$ is a local bisection of the corresponding Lie groupoid. The section of the source map associated with it is by construction the restriction of Φ_t^a to M . As a consequence, bisections can be seen as being obtained from integrating sections of a Lie algebroid.

2 Rackoids

In a first approach to the definition of Lie rackoids, we will discuss in this section the discrete version of a Lie rackoid, called simply a rackoid. The manifold version, i.e. Lie rackoids, will come up later. Note that not all rackoids that we are aware of are Lie rackoids, see propositions 2.12 and corollary 2.13 below.

2.1 Racks

First recall the notion of a rack, generalizing the conjugation operation in a group.

Definition 2.1. A *rack* consists of a set X equipped with a binary operation denoted $(x, y) \mapsto x \triangleright y$ such that for all x, y , and $z \in X$, the map $y \mapsto x \triangleright y$ is bijective and

$$x \triangleright (y \triangleright z) = (x \triangleright y) \triangleright (x \triangleright z).$$

Obviously, a group G with the conjugation operation $g \triangleright h := ghg^{-1}$ for all $g, h \in G$ is an example of a rack. Observe that any conjugacy class or union of conjugacy classes is still a rack for this operation, while it is not a group in general. Let us recall the notion of an augmented rack:

Definition 2.2. Let G be a group and X be a G -set. We say that X together with a map $p : X \rightarrow G$ is an *augmented rack* when it satisfies the augmentation identity, i.e.

$$p(g \cdot x) = gp(x)g^{-1}$$

for all $g \in G$ and all $x \in X$.

An augmented rack is not strictly speaking a rack, but gives rise to a genuine rack structure on the set X :

Proposition 2.3. Suppose $p : X \rightarrow G$ is an augmented rack. Then setting for all $x, y \in X$,

$$x \triangleright y := p(x) \cdot y$$

endows X with the structure of a rack.

Proof. We give a proof here for further reference. For all $x, y, z \in X$, a direct computation yields the rack identity:

$$\begin{aligned}
(x \triangleright y) \triangleright (x \triangleright z) &= p(p(x) \cdot y) \cdot (p(x) \cdot z) \\
&= (p(x)p(y)p(x)^{-1}) \cdot (p(x) \cdot z) \\
&= p(x) \cdot (p(y) \cdot z) \\
&= x \triangleright (y \triangleright z).
\end{aligned}$$

□

We will see in section 2.4 how this construction mechanism generalizes to rackoids. Units can be considered in the framework of racks; the corresponding notion is that of a pointed rack:

Definition 2.4. A rack X is *pointed* in case there exists an element $1 \in X$ such that for all $x \in X$

$$1 \triangleright x = x, \quad x \triangleright 1 = 1.$$

Once again, the conjugation rack of a group is an example of a pointed rack.

Definition 2.5. A *Lie rack* X is a manifold which carries a pointed rack structure such that all the structure maps are smooth and for all $x \in X$, the smooth map $y \mapsto x \triangleright y$ is a diffeomorphism.

We take Lie racks to be pointed in order to be able to construct their tangent Leibniz algebra on the tangent space at the distinguished point (see Theorem 3.4 in [9]).

2.2 Definition of a rackoid

Definition 2.6. A small *precategory* is a pair of sets (Γ, M) together with surjective maps $s, t : \Gamma \rightarrow M$ and a map $\epsilon : M \rightarrow \Gamma$ such that $s \circ \epsilon = t \circ \epsilon = \text{id}_M$. In general, we shall use the shorthand $1_m = \epsilon(m)$.

Obviously, a precategory with a composition map $\text{comp} : \Gamma \times_M \Gamma \rightarrow \Gamma$ is a category. A pair of sets (Γ, M) together with surjective maps $s, t : \Gamma \rightarrow M$ will also be called a *semi-precategory*. This notion will be important for the non-unitary version of rackoids.

Definition 1.1 still makes sense for semi-precategories. We repeat it for convenience:

Definition 2.7. Let $\Gamma \xrightleftharpoons[t]{s} M$ be a semi-precategory over M . A *bisection* of Γ is any of two equivalent data:

- (i) a subset $\Sigma \subset \Gamma$ such that (the restrictions of) source and target maps $s : \Sigma \rightarrow M$ and $t : \Sigma \rightarrow M$ are bijective.
- (ii) a map $\sigma : M \rightarrow \Gamma$ which is right inverse to the source map s and for which $t \circ \sigma : M \rightarrow M$ is a bijection of M .

Of course, when a groupoid is considered as a semi-precateory, bisections in the sense of Definition 2.7 are exactly the bisections described in section 1.1.

We now define rackoids. For the sake of clarity, let us fix or recall some notation. For every pair of points $m, n \in M$, we denote by Γ_m^n the set of all elements in Γ with source m and target n . Again, for every bisection Σ , we denote by σ the corresponding right inverse of $s : \Sigma \rightarrow M$ and by $\underline{\sigma} : M \rightarrow M$ the bijection of M obtained as the composition $t \circ \sigma$.

Definition 2.8. A (non-unital) rackoid is a semi-precateory $\Gamma \xrightleftharpoons[t]{s} M$ with a composition law $\triangleright : (\Sigma, \gamma) \mapsto \Sigma \triangleright \gamma$ mapping a bisection Σ and an element $\gamma \in \Gamma_m^n$ to an element in $\Gamma_{\underline{\sigma}(m)}^{\underline{\sigma}(n)}$.² We require that:

1. for all bisections Σ , the assignment $\Sigma \triangleright - : \Gamma \rightarrow \Gamma$ is a bijection³,
2. the composition law is supposed to satisfy the self-distributivity relation

$$\Sigma \triangleright (\mathcal{T} \triangleright \gamma) = (\Sigma \triangleright \mathcal{T}) \triangleright (\Sigma \triangleright \gamma) \quad (2)$$

for all bisections Σ, \mathcal{T} and all $\gamma \in \Gamma$.

Furthermore, in order to define a *unital or pointed rackoid*, in case Γ is a precateory, we require the composition law to satisfy $1_M \triangleright \gamma = \gamma$ and $\sigma \triangleright 1_m = 1_{\underline{\sigma}(m)}$ for all $m \in U$. Here we write 1_m for the unit at m , i.e. $1_m = \epsilon(m)$ and by 1_M the bisection $\epsilon(M)$.

As expected, a rackoid over a point (i.e. when M is a point in definition 2.8) is a rack. It is not true in general that the vertex- or isotropy sets $\Gamma_m^m := s^{-1}(m) \cap t^{-1}(m)$ become racks.

This is true, however, under the following conditions:

Proposition 2.9. Let Γ be a rackoid over M and $m \in M$ be some element such that $\Gamma_m^m \neq \emptyset$. Assume that there is a bisection through each point $\gamma' \in \Gamma_m^m$ and that $\Sigma_1 \triangleright \gamma = \Sigma_2 \triangleright \gamma$ for every bisections Σ_1, Σ_2 through γ' , then the isotropy sets $\Gamma_m^m := s^{-1}(m) \cap t^{-1}(m)$ become racks via the induced operation.

The rack Γ_m^m described in the previous proposition is called *isotropy rack* in at m of the rackoid Γ .

Rackoids have permanence properties quite different from those of groupoids or even of racks:

Proposition 2.10. For all rackoid Γ , the subset $\{\gamma \in \Gamma | s(\gamma) \neq t(\gamma)\}$ is a rackoid.

²Equivalently, for all bisections Σ and all elements $\gamma \in \Gamma$, the composition $\sigma \triangleright \gamma$ is defined to be an element of Γ whose source is $\underline{\sigma} \circ s(\gamma)$ and whose target is $\underline{\sigma} \circ t(\gamma)$.

³It is then automatic that for every bisection \mathcal{T} , the image of $\mathcal{T} \subset \Gamma$ under $\Sigma \triangleright -$, subset that we shall denote by $\Sigma \triangleright \mathcal{T}$, is a bisection again, and that $\underline{\sigma \triangleright \mathcal{T}} = \underline{\sigma} \circ \underline{\mathcal{T}} \circ \underline{\sigma}^{-1}$.

Proof. If $x \in \Gamma$ has $s(x) = m \in M$ and $t(x) = n \neq m$ with $n, m \in U$, then for all bisections $\sigma \in \text{Bis}(\Gamma)$, we have that $s(\sigma \triangleright x) = \underline{\sigma}(m)$ and $t(\sigma \triangleright x) = \underline{\sigma}(n) \neq \underline{\sigma}(m)$ by bijectivity. Therefore the subset of elements where source and target are different is preserved by the rack operations. \square

We will not admit the empty set as a rackoid and we will furthermore implicitly assume that all our (semi-) precategories do admit bisections (otherwise the axioms are empty).

2.3 Groupoids as rackoids

The first example of a rackoid is of course a groupoid. For Γ a groupoid over M , the composition rule defined for all bisection Σ and γ , by

$$\Sigma \triangleright \gamma = \Sigma \star \{\gamma\} \star \Sigma^{-1} \quad (3)$$

defines a rackoid structure. Recall that \star is the operation defined in (1), see Section 1.1.

Proposition 2.11. The conjugation operation (3) in a groupoid gives rise to a rack product on bisections, rendering the groupoid a rackoid.

Proof. This follows directly from Section 1.1 and definition 2.8 which is modeled onto the conjugacy rackoid underlying a groupoid. \square

By the *orbit* of an element γ in a groupoid Γ , we mean an orbit of $s(\gamma)$ under the natural action of a groupoid on its unit space. Isotropy groups over elements in a given orbit O form a group bundle over M . For all $m, n \in M$, conjugation by an arbitrary element $\gamma \in \Gamma_m^n$ induces a group automorphism and different choices for γ lead to automorphisms that differ by inner group morphisms. In particular, the isotropy groups associated to any two elements in the same orbit are conjugated.

By the *conjugacy class* of an element γ in a groupoid Γ that we assume to admit a bisection through any of its element, we mean the set of all elements of the form $\Sigma \triangleright \gamma$ for Σ a bisection of Γ . If $s(\gamma) \neq t(\gamma)$, then the conjugacy class of γ is made of all elements $\{\gamma' \in \Gamma_O^O \mid s(\gamma') \neq t(\gamma')\}$ with O being the orbit of γ . If $s(\gamma) = t(\gamma)$, then the conjugacy class of γ is made of the collection of all the orbits in the isotropy groups of the orbits of γ that correspond to the conjugacy group of $\gamma \in \Gamma_m^m$. In any case, the following result is true:

Proposition 2.12. Each conjugacy class in a groupoid is a rackoid.

Corollary 2.13. Identify, in a Lie groupoid, two elements γ and γ' if and only if $s(\gamma) = s(\gamma')$ and $t(\gamma) = t(\gamma')$. The set of equivalence classes is a rackoid (and even a groupoid).

2.4 Augmented rackoids

In the present section, we generalize to rackoids the mechanism which constructs racks out of augmented racks.

Theorem 2.14. *Let $\Gamma \xrightleftharpoons[t']{s'} M$ be a groupoid and $X \xrightleftharpoons[t]{s} M$ be a precategory. Suppose that there exists a morphism of precategories $p : X \rightarrow \Gamma$, i.e. a map such that*

1. *The map p intertwines⁴ the sources and targets of X and Γ :*

$$\begin{array}{ccc} X & \xrightarrow{p} & \Gamma \\ \downarrow t & \downarrow s & \downarrow t' \\ M & \xrightarrow{\text{id}_M} & M \end{array}$$

2. *The map p intertwines the identity maps $\epsilon : M \rightarrow X$ and $\epsilon' : M \rightarrow \Gamma$:*

$$\begin{array}{ccc} X & \xrightarrow{p} & \Gamma \\ \epsilon \uparrow & & \uparrow \epsilon' \\ M & \xrightarrow{\text{id}_M} & M \end{array}$$

Suppose that the group of bisections $\text{Bis}(\Gamma)$ acts on X in such a manner that for all $\Sigma \in \text{Bis}(\Gamma)$ and all $x \in X$:

$$p(\Sigma \cdot x) = \Sigma \star p(x) \star \Sigma^{-1}, \quad (4)$$

while for all $m \in M$

$$p(\Sigma) \cdot 1'_m = 1'_m. \quad (5)$$

where, as usual, $1'_m = \epsilon'(m)$.

Then the prescription

$$\mathcal{T} \triangleright x := p(\mathcal{T}) \cdot x$$

defines for all $x \in X$ and all bisections \mathcal{T} of X a pointed rackoid structure on X .

Proof. Observe that the first commutative diagram implies that p induces a map

$$p : \text{Bis}(X) \rightarrow \text{Bis}(\Gamma)$$

between sets of bisections. Observe further that the augmentation identity (4) implies that $s(g \cdot x) = \underline{g}(s(x))$ and $t(g \cdot x) = \underline{g}(t(x))$ where \underline{g} is the diffeomorphism associated to the bisection g . The autodistributivity relation follows as in the

⁴Note that this condition implies that the p -image of a bisection of X is a bisection of Γ .

proof of Proposition 2.3 from the augmentation identity (4). The map p sends identities to identities, i.e. (5) holds, thus for all $m \in M$ and all $x, y \in X$:

$$1_m \triangleright y = p(1_m) \cdot y = 1'_m \cdot y = y,$$

and by hypothesis,

$$x \triangleright 1_m = p(x) \cdot 1'_m = 1'_m.$$

□

A context where this can be applied is the following; we use here the non-unitary version of a rackoid and the corresponding non-unitary version of the above theorem, formulated in terms of semi-precategories instead of precategories.

Let $q : Y \rightarrow M$ be a surjective map. Let Γ be a groupoid $\Gamma \xrightleftharpoons[t']{s'} M$ that acts freely and transitively on the fibers of q . Consider the fiber product $X := Y \times_{q, M, q} Y$ and define

$$p : X \rightarrow \Gamma, \quad x = (y_1, y_2) \mapsto \gamma,$$

by choosing as γ the unique element such that $y_1 = \gamma \cdot y_2$. Let a bisection $\sigma \in \text{Bis}(\Gamma)$, seen as a section of the source map s , act on X by

$$\sigma \cdot (y_1, y_2) := (\sigma(y_1) \cdot y_1, \sigma(y_2) \cdot y_2),$$

where one multiplies with the unique element $\sigma(y)$ in the bisection σ such that the composition makes sense. By construction,

$$p(\sigma \cdot (y_1, y_2)) := \sigma(y_2)p(y_1, y_2)\sigma(y_1)^{-1}.$$

Applying the (non-unitary version of the) above theorem yields a (non-unitary) rackoid structure on $X = Y \times_{q, M, q} Y$. We will exploit this example in the smooth framework in section 6.3.

3 Lie rackoids

3.1 Manifold structure on bisections

In the following, we will work with smooth precategories (and - without explicitly transcribing everything - with smooth semi-precategories).

Definition 3.1. A *smooth precategory* is a pair of smooth manifolds (Γ, M) together with surjective submersions $s, t : \Gamma \rightarrow M$ and a smooth map $\epsilon : M \rightarrow \Gamma$ (mapping $m \in M$ to $1_m = \epsilon(m) \in \Gamma$) such that $s \circ \epsilon = t \circ \epsilon = \text{id}_M$.

Here for "smooth manifold" we break with the tradition which admits Lie groupoids such that Γ is a non-necessarily Hausdorff, non-necessarily second countable smooth manifold. In our setting, "smooth manifold" always means

that Γ is a Hausdorff, non-necessarily second countable (because Γ can be an infinite-dimensional manifold) smooth manifold, while M is supposed to be a Hausdorff, second countable smooth manifold. In fact, we will always suppose M to be compact. Here comes the definition of bisections in the smooth framework.

Definition 3.2. A *smooth bisection* of a smooth precategory $\Gamma \xrightleftharpoons[t]{s} M$ is a bisection $\Sigma \subset \Gamma$ such that the associated right inverse to $s : \Gamma \rightarrow M$ is a smooth map and such that the bijective map $\underline{\sigma}$ is a diffeomorphism.

Notice that smooth bisections are precisely the submanifolds of Γ to which the restriction of both s and t are diffeomorphism onto M .

In the special case where $\Gamma \xrightleftharpoons[t]{s} M$ is a Lie groupoid, the smooth bisections from the above definition are exactly the smooth bisections we have discussed earlier.

Let us still denote by $\text{Bis}(\Gamma)$ the set of all smooth bisections. We also still denote by $\underline{\sigma} = t \circ \sigma : m \rightarrow t(\sigma(m))$ the corresponding diffeomorphism of M .

Let us show that the set of (smooth) bisections of a smooth precategory (and also of a smooth semi-precategory) has the structure of an infinite-dimensional manifold. This structure is closely related to the Lie group structure on the set of bisection of a Lie groupoid by Schmeding and Wockel, see [17].

Proposition 3.3. Let $\Gamma \xrightleftharpoons[t]{s} M$ be a smooth precategory with compact base manifold M . Then the set of bisections $\text{Bis}(\Gamma)$ carries a structure of a Fréchet manifold.

Proof. By Proposition 10.10 in [15], the space of all sections $S_s(M, \Gamma)$ of the surjective submersion $s : \Gamma \rightarrow M$ is a splitting submanifold of the Fréchet manifold $\mathcal{C}^\infty(M, \Gamma)$ (equipped with the \mathcal{C}^∞ topology).

On the other hand, the composition with the smooth target map t is a smooth map

$$t_* : \mathcal{C}^\infty(M, \Gamma) \rightarrow \mathcal{C}^\infty(M, M),$$

and this remains true for its restriction to the submanifold $S_s(M, \Gamma)$. By Corollary 5.7 of [15], the subgroup of diffeomorphisms $\text{Diff}(M) \subset \mathcal{C}^\infty(M, M)$ is open and acquires thus its Fréchet manifold structure. By construction, the set $\text{Bis}(\Gamma) = (t_*)^{-1}(\text{Diff}(M))$ is therefore an open submanifold of $S_s(M, \Gamma)$, and thus an open submanifold of $\mathcal{C}^\infty(M, \Gamma)$. \square

Corollary 3.4. With respect to this manifold structure on $\text{Bis}(\Gamma)$, a family of bisections σ_s with s in a neighborhood \mathcal{U} of 0 in \mathbb{R}^n is smooth if and only if the function $(u, m) \rightarrow \sigma_u(m)$ is a smooth function from $\mathcal{U} \times M$ to Γ .

Proof. This follows immediately from the so-called exponential law, see Theorem A in [1]. \square

3.2 Definition of Lie rackoids

Here comes the definition of a Lie rackoid, i.e. the smooth version of a rackoid. We suppose in the following definition the set of bisections $\text{Bis}(\Gamma)$ to be endowed with the Fréchet manifold structure defined in the preceding subsection.

Definition 3.5. A Lie rackoid is a smooth precategory $\Gamma \xrightleftharpoons[t]{s} M$ with a smooth composition law $\triangleright : (\Sigma, \gamma) \mapsto \Sigma \triangleright \gamma \in \Gamma$ for all bisections $\Sigma \in \text{Bis}(\Gamma)$ and all $\gamma \in \Gamma$ such that $\Sigma \triangleright - : \Gamma \rightarrow \Gamma$ is a smooth diffeomorphism for all $\Sigma \in \text{Bis}(\Gamma)$.

This composition law is supposed to satisfy the self-distributivity relation

$$\Sigma \triangleright (\mathcal{T} \triangleright \gamma) = (\Sigma \triangleright \mathcal{T}) \triangleright (\Sigma \triangleright \gamma) \quad (6)$$

for all $\Sigma \in \text{Bis}(\Gamma)$, $\mathcal{T} \in \text{Bis}(\Gamma)$ and all $\gamma \in \Gamma$.

The composition law is supposed to be compatible with the source and target map in the sense that

$$s(\Sigma \triangleright \gamma) = \underline{s}(s(\gamma)), \quad t(\Sigma \triangleright \gamma) = \underline{t}(t(\gamma))$$

for all $\Sigma \in \text{Bis}(\Gamma)$ and all $\gamma \in \Gamma$.

Furthermore, the composition law should satisfy $1_M \triangleright \gamma = \gamma$ with $1_M = \epsilon(M)$ and $\Sigma \triangleright 1_m = 1_{\underline{s}(m)}$ for all $m \in M$.

Observe that a Lie rackoid is not a rackoid in the sense of Definition 2.8 as the rack product is only defined on the set of smooth bisections and not on the set of all bisections.

Remark 3.6. We have defined a Lie rackoid only using global bisections, because we wanted to avoid that the rackoid-product of a bisection Σ and a $\gamma \in \Gamma$ depends only on the germs of the bisection at the source and the target of γ . In our examples, it turns out to depend on the whole bisection. Nevertheless, the corresponding local definition (i.e. using only local bisections) for a Lie rackoid also makes sense and gives a (a priori) different version of Lie rackoid where the product does only depend on the germs of the bisections at source and target.

As before, we have:

Proposition 3.7. Let Γ be a Lie rackoid over M and $m \in M$ be some element such that $\Gamma_m^m \neq \emptyset$. Assume that there is a smooth bisection through each point $\gamma' \in \Gamma_m^m$ and that $\Sigma_1 \triangleright \gamma = \Sigma_2 \triangleright \gamma$ for every bisections Σ_1, Σ_2 through γ' , then the isotropy sets Γ_m^m become Lie racks via the induced operation.

Note that the hypothesis of possessing enough smooth bisections (i.e. at least one through every point of the groupoid) is for example fulfilled in the case of a source-connected Lie groupoid, see [2].

4 Bundles of Lie racks as Lie rackoids

Let us here discuss a very explicit example of a Lie rackoid, namely a bundle of Lie racks. In this case we have $s = t$ for the source and target maps of the underlying precategory.

The following proposition is straightforward.

Proposition 4.1. A bundle of Lie racks endows a natural Lie rackoid structure, with respect to the product given by $\Sigma \triangleright \gamma = \sigma(m) \triangleright_m \gamma$ for all $m \in M$, with γ an arbitrary point in the fiber over m , fiber whose rack product we denote by \triangleright_m , and Σ a bisection, seen as a section σ of the projection onto the base manifold.

Below is an example of non-trivial bundle of Lie rack.

The idea is here to construct a “jump deformation” from a 4-dimensional very elementary example of a Lie rack (due to S. Covez in his PhD thesis (p.78)). Namely, for $t \in \mathbb{R}$, let $\mathfrak{g}_t := \mathbb{R}^4$ be the Leibniz algebra defined by the bilinear map

$$[\cdot, \cdot]_t : \mathfrak{g}_t \times \mathfrak{g}_t \rightarrow \mathfrak{g}_t$$

which is set to be

$$[(x_1, x_2, x_3, x_4), (y_1, y_2, y_3, y_4)]_t := (0, 0, 0, tx_1y_1 + x_1y_2 - x_2y_1 + tx_2y_2 + tx_3y_3).$$

Observe that the terms which render this Leibniz bracket non-Lie are multiplied by $t \in \mathbb{R}$, so for $t = 0$, this is a genuine Lie algebra, while for $t \neq 0$, it is a non-Lie Leibniz algebra. As Covez explains, \mathfrak{g}_1 (and thus also \mathfrak{g}_t for $t \neq 0$) is a non-split Leibniz algebra, i.e. it is not isomorphic to a hemisemidirect product of a Lie algebra and a representation.

Covez integrates the Leibniz bracket $[\cdot, \cdot]_t$ on \mathbb{R}^4 into a Lie rack structure on \mathbb{R}^4 . Our idea is to do this here “in families”, the non-triviality of our Leibniz algebra bundle coming from the fact that it degenerates to a Lie algebra at $t = 0$. Obviously, the two parts $(\mathfrak{g}_t)_{\text{Lie}}$ and $Z_L(\mathfrak{g}_t)$ integrate to the trivial Lie racks \mathbb{R}^3 and \mathbb{R} respectively.

Writing down the explicit formula for the rack cocycle f_t obtained from integrating the Leibniz cocycle ω_t , it turns out that for all $a = (a_1, a_2, a_3, a_4), b = (b_1, b_2, b_3, b_4) \in \mathbb{R}^4$, $f_t(a, b) = \omega_t(a, b)$, the explicit formula for the Lie rack structure \triangleright_t on \mathbb{R}^4 is

$$(a_1, a_2, a_3, a_4) \triangleright_t (b_1, b_2, b_3, b_4) = (b_1, b_2, b_3, ta_1b_1 + ta_2b_2 + ta_3b_3 + a_1b_2 - a_2b_1 + b_4).$$

Observe that for $t = 0$ the rack structure is the conjugation in the standard semi-direct product group

$$(a_1, a_2, a_3, a_4) \cdot (b_1, b_2, b_3, b_4) = (a_1 + b_1, a_2 + b_2, a_3 + b_3, a_4 + b_4 + a_1b_2).$$

Theorem 4.2. *The manifold \mathbb{R}^5 with the above structure \triangleright_t and the projection onto \mathbb{R} given by $(a_1, a_2, a_3, a_4, t) \mapsto t$ is a (non-trivial) bundle of Lie racks, i.e. it is not isomorphic (as Lie racks) to a direct product of the trivial Lie rack \mathbb{R} with some Lie rack \mathbb{R}^4 .*

Proof. The proof is very simple: In case the bundle was trivial, the isomorphism type of the Lie rack should be constant. But this is not the case, as the Lie rack degenerates to a conjugation rack coming from a Lie group at $t = 0$. \square

5 Lie rackoids generalize Lie groupoids

In this section, we highlight two propositions which show in which sense Lie rackoids generalize Lie groupoids: Any Lie groupoid gives rise to a Lie rackoid via conjugation, and any Lie rackoid defines a tangent Leibniz algebroid.

5.1 The Lie rackoid underlying a Lie groupoid

In the smooth framework, we have the following proposition which strenghtens Proposition 2.11.

Proposition 5.1. A Lie groupoid defines a Lie rackoid via conjugation.

Proof. A Lie groupoid $\Gamma \underset{t}{\overset{s}{\rightrightarrows}} M$ has obviously an underlying smooth precategory $\Gamma \underset{t}{\overset{s}{\rightrightarrows}} M$. The bisections (with respect to the precategory structure) are then just the ordinary bisections of the Lie groupoid (see Definition 3.2 and [13] p. 22). Observe that for each bisection $\Sigma \in \text{Bis}(\Gamma)$, we have an inverse bisection $\Sigma^{-1} \in \text{Bis}(\Gamma)$ (see *loc. cit.* p. 22), still right inverse to the source map, but such that $t \circ \sigma^{-1}$ is the inverse of the diffeomorphism $t \circ \sigma : M \rightarrow M$.

We define for all $\Sigma \in \text{Bis}(\Gamma)$ and all $\gamma \in \Gamma$ the composition law $\triangleright : (\Sigma, \gamma) \mapsto \Sigma \triangleright \gamma \in \Gamma$ using the conjugation, i.e. $\Sigma \triangleright \gamma := \Sigma \gamma \Sigma^{-1}$. It is clear (from the associativity of the groupoid operation for composable elements) that \triangleright satisfies the self-distributivity relation. It is still more obvious that $1_M \triangleright \gamma = \gamma$ with $1_M = \epsilon(M)$ and $\Sigma \triangleright 1_m = 1_{\sigma(m)}$ for all $m \in M$.

The operation \triangleright is clearly smooth with respect to the Fréchet manifold structure on $\text{Bis}(\Gamma)$ by Corollary 3.4. \square

5.2 From Lie rackoids to Leibniz algebroids

Recall the definition of a Leibniz algebroid from [8].

Definition 5.2. A Leibniz algebroid is the data of a vector bundle $\pi : A \rightarrow M$ together with a Leibniz algebra structure on the space of global sections $\Gamma(A)$ and a bundle morphism $\rho : A \rightarrow TM$ (the anchor) such that ρ (on the level of sections) is a Leibniz morphism and for all $b, a \in \Gamma(A)$ and all $f \in C^\infty(M)$

$$[b, fa] = f[b, a] + \rho(b)(f) a. \quad (7)$$

Note that, since the bracket is a priori not skew-symmetric, there is no way to express $[fs_1, s_2]$, and it has no reason to be $f[s_1, s_2] - \rho(s_2)(f)s_1$ in general.

From now, and until the end of this section, we assume that M is a compact manifold.

Theorem 5.3. *A Lie rackoid over a compact manifold gives rise to a tangent Leibniz algebroid.*

We shall give a more precise statement in Theorem 5.8 below.

Let $\Gamma \xrightleftharpoons[t]{s} M$ be a pointed Lie rackoid. Consider the pull-back $\epsilon^*T\Gamma$ of $T\Gamma \rightarrow \Gamma$ through $\epsilon : M \hookrightarrow \Gamma$. By construction, the fiber of $\epsilon^*T\Gamma$ over $m \in M$ is $T_{1_m}M$. There are therefore two submersive vector bundle maps Ts, Tt from $\epsilon^*T\Gamma$ to TM , obtained by differentiating the source and target maps

$$T_{1_m}t : T_{1_m}\Gamma \rightarrow T_mM \text{ and } T_{1_m}s : T_{1_m}\Gamma \rightarrow T_mM.$$

We define a vector bundle A that we call *infinitesimal Leibniz algebroid* by considering the kernel of $Ts : \epsilon^*T\Gamma \rightarrow TM$. In equation:

$$A := \ker(Ts) = \coprod_{m \in M} \ker(T_{1_m}s) \subset \coprod_{m \in M} T_{1_m}\Gamma = \epsilon^*T\Gamma. \quad (8)$$

We then define the *anchor map* to be a vector bundle morphism ρ from A to TM obtained by restricting to $A \subset \epsilon^*T\Gamma$ the vector bundle submersion $Tt : \epsilon^*T\Gamma \rightarrow TM$, up to a sign. In equation:

$$\rho = -Tt|_A. \quad (9)$$

So far, the construction is parallel to the construction of the Lie algebroid associated to a Lie groupoid.

We shall need the next technical lemma, in which I is a shorthand for the interval $] -1, +1[$, the topology on $\text{Bis}(\Gamma)$, the Fréchet manifold topology used in Proposition 3.3 and Corollary 3.4, is implicitly used to justify the existence of the derivative that appears in it:

Lemma 5.4. For every section of A seen as a map from M to $T\Gamma$ mapping m to $b_m \in A_m \subset T_{1_m}M$, there exists a smooth family $(\Sigma_u)_{u \in I}$ of bisections of Γ such that $\Sigma_0 = \epsilon(M)$ and $\frac{\partial}{\partial u}|_{u=0} \sigma_u(m) \subset T_{1_m}\Gamma$ coincides with b_m for all $m \in M$. Conversely, for any smooth family $(\Sigma_u)_{u \in I}$ in $\text{Bis}(\Gamma)$, such that $\Sigma_0 = \epsilon(M)$, the assignment $m \mapsto \frac{\partial}{\partial u}|_{u=0} \sigma_u(m)$ is a smooth section of A .

Proof. Let \tilde{b} be a vector field, supported in a neighborhood of $\epsilon(M) \subset \Gamma$, tangent to the fibers of s , and extending b , i.e. such that the restriction of \tilde{b} to $\epsilon(M)$ coincides with b . Let $\sigma_u(m)$ be the flow at the time u starting at 1_m of \tilde{b} . It is by construction true that $\frac{\partial}{\partial u}|_{u=0} \sigma_u(m) \subset T_{1_m}\Gamma$ coincides with b_m . Moreover, upon replacing \tilde{b} by $\chi\tilde{b}$ with χ a function supported in a neighborhood of $\epsilon(M) \subset$

Γ and equal to 1 on that manifold, we can assume that $\sigma_u(m)$ is defined for all $u \in I$ and that, for all fixed $u \in I$, $m \rightarrow \sigma_u(m)$ is a bisection Σ_u of Γ . According to Corollary 3.4, it is a smooth family of bisections, which completes the first part of the proof.

The second part follows from Corollary 3.4, which grants that

$$m \mapsto \left. \frac{\partial}{\partial u} \right|_{u=0} \sigma_u(m)$$

is a smooth section of $\epsilon^*T\Gamma$ and the relation $s \circ \sigma_u = id_M$, which grants that $\left. \frac{\partial}{\partial u} \right|_{u=0} \sigma_u(m)$ has values in the kernel of $T_{1_m}s$, i.e. A_m . \square

Lemma 5.4 means that, when $\text{Bis}(\Gamma)$ is equipped with the Fréchet manifold topology as in Proposition 3.3:

Proposition 5.5. The tangent space of $\text{Bis}(\Gamma)$ at the bisection $\epsilon(M)$ is $\Gamma(A)$.

We can now define the adjoint action of a bisection $\Sigma \in \text{Bis}(\Gamma)$ on A . Let $\underline{\sigma}$ be the diffeomorphism of M associated to Σ and let

$$\begin{aligned} \Sigma^{\triangleright} : \quad \Gamma &\rightarrow \Gamma \\ \gamma &\rightarrow \Sigma \triangleright \gamma. \end{aligned}$$

By the definition 2.8 of a Lie rackoid, the following diagrams commute:

$$\begin{array}{ccc} M & \xrightarrow{\underline{\sigma}} & M \\ \downarrow \epsilon & & \downarrow \epsilon \\ \Gamma & \xrightarrow{\Sigma^{\triangleright}} & \Gamma \end{array} \quad \text{and} \quad \begin{array}{ccc} \Gamma & \xrightarrow{\Sigma^{\triangleright}} & \Gamma \\ \downarrow s & & \downarrow s \\ M & \xrightarrow{\underline{\sigma}} & M \end{array}.$$

Differentiating at the point $\gamma = 1_m$ (that in the next lines we write simply as m , making no further reference to the injection ϵ), the first of these diagrams, gives that $T_m \Sigma^{\triangleright}$ maps $T_m M$ to $T_{\underline{\sigma}(m)} M$. Differentiating at the point $m \in M$ the second of these diagrams yields:

$$\begin{array}{ccc} T_m \Gamma & \xrightarrow{T_m \Sigma^{\triangleright}} & T_{\underline{\sigma}(m)} \Gamma \\ \downarrow T_m s & & \downarrow T_{\underline{\sigma}(m)} s \\ T_m M & \xrightarrow{T_m \underline{\sigma}} & T_{\underline{\sigma}(m)} M \end{array}$$

which implies that $T_m \Sigma^{\triangleright}$ maps the kernel of $T_m s$ to the kernel of $T_{\underline{\sigma}(m)} s$, i.e. maps A_m to $A_{\underline{\sigma}(m)}$. We call *adjoint map* and denote by Ad_{Σ} the restricted vector bundle morphism. In equation:

$$\text{Ad}_{\Sigma} := T_m \Sigma^{\triangleright} \big|_A. \quad (10)$$

The inverse $(\Sigma^{\triangleright})^{-1}$ of Σ^{\triangleright} exists by assumption and its differential at $\epsilon(M)$ is the inverse of Ad_{Σ} . Hence, Ad_{Σ} is an invertible vector bundle morphism over

the diffeomorphism $\underline{\sigma}$. In particular, Ad_Σ can be seen as a linear operator on the space $\Gamma(A)$ of sections of A that we still denote by Ad_Σ with a slight abuse of notation: For every section $a \in \Gamma(A)$, we set $\text{Ad}_\Sigma a$ to be the section of A whose value at $m \in M$ is $\text{Ad}_\Sigma a_{\underline{\sigma}^{-1}(m)}$. In equation:

$$(\text{Ad}_\Sigma a)(m) = \text{Ad}_\Sigma a_{\underline{\sigma}^{-1}(m)} \text{ for all } m \in M. \quad (11)$$

Without going any further, notice that, for every smooth function f on M and every section a of A :

$$\text{Ad}_\Sigma f a = (\underline{\sigma}^{-1})^* f (\text{Ad}_\Sigma a). \quad (12)$$

The adjoint action can also be interpreted as follows.

Lemma 5.6. For every bisection $\Sigma \in \text{Bis}(\Gamma)$, the assignment $\mathcal{T} \mapsto \Sigma \triangleright \mathcal{T}$ is a smooth diffeomorphism of $\text{Bis}(\Gamma)$, mapping $\epsilon(M)$ to itself, and whose differential at the point $\epsilon(M)$ is, upon identifying $T_{\epsilon(M)}\text{Bis}(\Gamma)$ with $\Gamma(A)$ as in Proposition 5.5, is the adjoint action $\text{Ad}_\Sigma : \Gamma(A) \rightarrow \Gamma(A)$ given by (10).

This lemma implies immediately the following result:

Lemma 5.7. The adjoint action $\text{Bis}(\Gamma) \times \Gamma(A) \rightarrow \Gamma(A)$ is smooth, with $\text{Bis}(\Gamma), \Gamma(A)$ being equipped with the Fréchet topology.

Notice also that for every pair of bisections Σ, \mathcal{T} , relation (2) reads

$$\Sigma^\triangleright \circ \mathcal{T}^\triangleright = (\Sigma \triangleright \mathcal{T})^\triangleright \circ \Sigma^\triangleright.$$

This implies, when differentiated at a point $m \in M$ in the direction of $a \in A_m \subset T_m \Gamma$ that

$$\text{Ad}_\Sigma \circ \text{Ad}_\mathcal{T} a = \text{Ad}_{\Sigma \triangleright \mathcal{T}} \circ \text{Ad}_\Sigma a. \quad (13)$$

Lemma 5.7 allows to consider the differential of the assignment $(\Sigma, a) \mapsto \text{Ad}_\Sigma a$ from $\text{Bis}(\Gamma) \times \Gamma(A) \rightarrow \Gamma(A)$ at the bisection $\Sigma = \epsilon(M)$. Since by Proposition 5.5, the tangent space of $\text{Bis}(\Gamma)$ at $\epsilon(M)$ is precisely $\Gamma(A)$, this differential is a continuous assignment $\Gamma(A) \times \Gamma(A) \rightarrow \Gamma(A)$ (with $\Gamma(A)$ equipped with the Fréchet topology) which is linear in both variables by construction. We call it the *Leibniz algebroid bracket* and denote it by $(b, a) \mapsto [b, a]$. By construction:

$$[b, a] = \left. \frac{\partial}{\partial u} \right|_{u=0} \text{Ad}_{\Sigma_u} a, \quad (14)$$

with $a, b \in \Gamma(A)$ and Σ_ϵ an arbitrary smooth family of bisections as in Lemma 5.4, i.e. $\Sigma_0 = \epsilon(M)$ and $\left. \frac{\partial}{\partial u} \right|_{u=0} \sigma_u(m) = b_m$.

We are now able to make the statement of Theorem 5.3 more precise.

Theorem 5.8. For every Lie rackoid Γ , the vector bundle defined in (8) equipped with the anchor map defined in (9) and the bracket defined in (14) is a Leibniz algebroid, called the tangent Leibniz algebroid of Γ .

Proof. We show the compatibility of the bracket with the multiplication by smooth functions $f \in \mathcal{C}^\infty(M)$. Relation (14), applied to a smooth family $(\Sigma_u)_{u \in I}$ of bisections corresponding to an arbitrary section $b \in \Gamma(A)$ as in Lemma 5.4, implies that for every function f :

$$\begin{aligned}
[b, fa] &= \left. \frac{\partial}{\partial u} \right|_{u=0} \text{Ad}_{\Sigma_u}(fa) \\
&= \left. \frac{\partial}{\partial u} \right|_{u=0} ((\underline{\sigma}_u)^{-1})^* f \text{Ad}_{\Sigma_u}(a) \\
&= f \left. \frac{\partial}{\partial u} \right|_{u=0} \text{Ad}_{\Sigma_u}(a) + \left. \frac{\partial}{\partial u} \right|_{u=0} ((\underline{\sigma}_u)^{-1})^* f a, \\
&= f[b, a] + \left. \frac{\partial}{\partial u} \right|_{u=0} ((\underline{\sigma}_u)^{-1})^* f a.
\end{aligned}$$

where we used (12) to go from the first to the second line. The proof now follows from the fact that the vector field obtained by differentiating at $u = 0$ the 1-parameter family of diffeomorphisms $\underline{\sigma}_u := t \circ \sigma_u$ has a value at $m \in M$ given by

$$Tt \left(\left. \frac{\partial}{\partial u} \right|_{u=0} (\sigma_u(m)) \right) = Tt(b_m) = -\rho(b_m)$$

where σ_u is, for all $u \in I$, the section of s corresponding to Σ_u (so that $\underline{\sigma}_u = t \circ \sigma_u$) and where Lemma 5.4 was used the definition of the anchor given by equation (9) in the last line. This implies that the vector field obtained by differentiating at $u = 0$ the 1-parameter family of diffeomorphisms $\underline{\sigma}_u^{-1}$ is $\rho(b)$ and that

$$\left. \frac{\partial}{\partial u} \right|_{u=0} ((\underline{\sigma}_u)^{-1})^* f = \rho(b)(f),$$

which completes the proof of (7).

Differentiating (13) with respect to \mathcal{T} at the bisection $\epsilon(M)$ yields, in view of Lemma 5.6, that, for every section $b \in \Gamma(A)$:

$$\text{Ad}_\Sigma([b, a]) = [\text{Ad}_\Sigma b, \text{Ad}_\Sigma a].$$

Lemma 5.7 implies the continuity of the Leibniz algebroid bracket, which allows to differentiate the previous expression with respect to Σ at the point 1_M in the direction of some $c \in \Gamma(A) \simeq T_{1_M} \text{Bis}(\Gamma)$. The relation obtained by this procedure is precisely:

$$[c, [b, a]] = [[c, b], a] + [b, [c, a]].$$

This completes the proof. \square

6 More Examples

6.1 A Lie rackoid integrating a hemisemidirect product Leibniz algebra

In this section, we present an example of Lie rackoids that comes neither from a Lie groupoid nor from a bundle of Lie racks. We will see that this Lie rackoid integrates the hemisemidirect product Leibniz algebra associated to the action of diffeomorphisms on 1-forms. For the notion of a hemisemidirect product Leibniz algebra, see [10].

Let M be an arbitrary manifold, we define a smooth precategory with base manifold M as follows: $\Gamma := T^*M \times M$, while $s, t : \Gamma \rightarrow M$ are respectively, the maps,

$$t(\alpha, n) = n \quad \text{and} \quad s(\alpha, n) = m$$

for all $m \in M$, $\alpha \in T_m^*M$, $n \in M$, and $1_m = (0_m, m)$ with 0_m the zero element in T_m^*M .

We first characterize its bisections:

Lemma 6.1. A bisection in $\text{Bis}(\Gamma)$ of $\Gamma \xrightleftharpoons[t]{s} M$ is of the form $(\omega_m, \varphi(m))$ with $\omega \in \Omega^1(M)$ a 1-form and $\varphi : M \rightarrow M$ a diffeomorphism.

This lemma allows us to see elements of $\text{Bis}(\Gamma)$ as pairs (ω, φ) with $\varphi \in \text{Diff}(M)$ and $\omega \in \Omega^1(M)$, an identification that we will use without further mention.

We now endow the precategory $\Gamma \xrightleftharpoons[t]{s} M$ with a rackoid structure as follows. For an arbitrary element $(\alpha, n) \in \Gamma$ with $\alpha \in T_m^*M$, $n \in M$, and for an arbitrary $(\omega, \varphi) \in \text{Bis}(M)$, we set:

$$(\omega, \varphi) \triangleright (\alpha, m) := ((\varphi^{-1})^* \alpha, \varphi(n)) \quad (15)$$

with the understanding that $\psi^* = (T_{\psi^{-1}(m)}^* \psi)$. Observe that

$$T_{(\varphi \circ \psi)^{-1}(m)}^* (\varphi \circ \psi) = T_{\psi^{-1}(\varphi^{-1}(m))}^* \psi \circ T_{\varphi^{-1}(m)}^* \varphi,$$

which we write in a short hand notation as $(\varphi \circ \psi)^* = \psi^* \circ \varphi^*$.

Our first claim is that the product above defines a Lie rackoid structure.

Proposition 6.2. Let M be a manifold, then the operation \triangleright defined in equation (15) is a Lie rackoid structure on $\Gamma \xrightleftharpoons[t]{s} M$.

Proof. First, we have to determine what the product \triangleright induces on bisections: It follows directly from (15) that for every bisection $(\omega, \varphi) \in \text{Bis}(\Gamma)$ and $(\eta, \psi) \in \text{Bis}(\Gamma)$, we have

$$(\eta, \psi) \triangleright (\omega, \varphi) := ((\psi^{-1})^* \omega, \psi \circ \varphi \circ \psi^{-1}) \quad (16)$$

As a consequence, for every pair $(\omega, \varphi) \in \text{Bis}(\Gamma)$ and $(\eta, \psi) \in \text{Bis}(\Gamma)$ and every $(\alpha, n) \in \Gamma$, we compute:

$$\begin{aligned}
& ((\eta, \psi) \triangleright (\omega, \varphi)) \triangleright ((\eta, \psi) \triangleright (\alpha, n)) \\
= & ((\psi^{-1})^* \omega, \psi \circ \varphi \circ \psi^{-1}) \triangleright ((\eta, \psi) \triangleright (\alpha, n)) && \text{by (16)} \\
= & ((\psi^{-1})^* \omega, \psi \circ \varphi \circ \psi^{-1}) \triangleright ((\psi^{-1})^* \alpha, \psi(n)) && \text{by (15)} \\
= & (((\psi \circ \varphi \circ \psi^{-1})^{-1})^* (\psi^{-1})^* \alpha, (\psi \circ \varphi \circ \psi^{-1}) \circ \psi(n)) && \text{by (15)} \\
= & (((\psi^{-1})^* \circ (\varphi^{-1})^*) \alpha, (\psi \circ \varphi)(n)) \\
= & (\psi, \eta) \triangleright ((\varphi, \omega) \triangleright (\alpha, n)) && \text{by (15)}
\end{aligned}$$

□

We now compute the Leibniz algebroid associated with it:

Proposition 6.3. Let M be a manifold, then the tangent Leibniz algebroid of the above Lie rackoid structure on $\Gamma \xrightarrow[t]{s} M$ is the vector bundle $TM \oplus T^*M$, equipped with the projection onto the first component as anchor and the bracket:

$$[X + \alpha, Y + \beta] = [X, Y] + \mathcal{L}_X \beta$$

for all $X, Y \in \mathcal{X}(M)$, $\alpha, \beta \in \Omega^1(M)$.

Proof. This formula can be indeed derived quite easily by differentiating (16), as in Theorem 5.3. □

Observe that the formula for the Leibniz bracket is exactly the Leibniz bracket of the hemisemidirect product associated to a Lie algebra (here the Lie algebra of vector fields) and a module (here the module of 1-forms), see Example 2.2 (p. 529) in [10].

6.2 Augmented Lie rackoids

The construction mechanism from Section 2.4 generalizes to the smooth setting. The following theorem also exists in a non-unital version which we will not spell out explicitly.

Theorem 6.4. Let $\Gamma \xrightarrow[t']{s'} M$ be a Lie groupoid and $X \xrightarrow[t]{s} M$ be a smooth precategory. Suppose that there exists a smooth map $p : X \rightarrow \Gamma$ such that:

$$\begin{array}{ccc}
X & \xrightarrow{p} & \Gamma \\
\downarrow t \quad \downarrow s & & \downarrow t' \quad \downarrow s' \\
M & \xrightarrow{\text{id}_M} & M
\end{array}$$

Suppose further that we have a commutative diagram for the identity maps $\epsilon : M \rightarrow X$ and $\epsilon' : M \rightarrow \Gamma$:

$$\begin{array}{ccc} X & \xrightarrow{p} & \Gamma \\ \epsilon \uparrow & & \uparrow \epsilon' \\ M & \xrightarrow{\text{id}_M} & M \end{array}$$

Suppose that the Lie groupoid $\text{Bis}(\Gamma)$ of bisections acts on X smoothly and that for all $g \in \text{Bis}(\Gamma)$ and all $x \in X$:

$$p(g \cdot x) = gp(x)g^{-1},$$

and that $p(x) \cdot 1_m = 1_m$ for all $x \in X$ and all $m \in M$.

Then the prescription

$$x \triangleright y := p(x) \cdot y$$

defines for $y \in X$ and a bisection x a Lie rackoid structure on X .

As examples for the preceding theorem, we can consider associated tensor bundles to the pair Lie groupoid $\Gamma \xrightleftharpoons[t']{s'} M$:

Corollary 6.5. Let Γ be a Lie groupoid over M . For every $q \in \mathbb{N}$, $\bigotimes^q T\Gamma$, $\Lambda^q T\Gamma$, $\bigotimes^q T^*\Gamma$ or $\Lambda^q T^*\Gamma$ admit natural Lie rackoid structures over M .

Let us discuss another application of Theorem 6.4.

Let M be a manifold. Take the Lie groupoid $T^*M \oplus T^*M \xrightleftharpoons[t]{s} M$. Its bisections are (like in Lemma 6.1) of the form $(\omega_m, \alpha_n, \phi)$ where $\omega_m \in T_m^*M$, $\alpha_n \in T_n^*M$ and ϕ is a diffeomorphism between open sets, sending m to $\phi(m) = n$. Take as the map p the forgetful map $p : T^*M \oplus T^*M \rightarrow M \times M$ with values in the pair groupoid $M \times M \xrightleftharpoons[t']{s'} M$. The bisections of the pair groupoid are diffeomorphisms ψ on M . These bisections act on $T^*M \oplus T^*M$ in a natural way, by composing diffeomorphism and acting via ψ^* on cotangent vectors. It is easy to see that the p -image of the action of ψ on $(\omega_m, \alpha_n, \phi)$ is the conjugation of ϕ by ψ . Therefore we are in position to apply the above theorem in order to obtain a rackoid structure on $T^*M \oplus T^*M$. This is another way to obtain the Lie rackoid which we described in Section 6.1:

Corollary 6.6. The Lie rackoid constructed in Section 6.1 can be obtained as a special case of Theorem 6.4 using the forgetful map p from the Lie groupoid $T^*M \oplus T^*M$ to the pair groupoid $M \times M$.

Let us also come back to a smooth version of the construction in Section 2.4.

Corollary 6.7. Let $q : Y \rightarrow M$ be a smooth fiber bundle such that a Lie groupoid $\Gamma \xrightleftharpoons[t']{s'} M$ acts freely and transitively on the fibers of q . Then the fiber product $X := Y \times_{q,M,q} Y$ becomes naturally a non-unitary Lie rackoid.

6.3 The fundamental rackoid

Here we explain a rackoid version of the fundamental rack defined e.g. in [6] p.358. In order to be close to their construction, we will work here with right racks instead of left racks, and consequently with right rackoids instead of left rackoids.

A *link* is a codimension two embedding $L : M \subset Q$ of manifolds. We will assume that M is non-empty, that Q is connected (with empty boundary) and that M is transversely oriented in Q . In other words, we assume that each normal disc to M in Q has an orientation which is locally and globally coherent.

The link is called *framed* if there is a cross-section $\lambda : M \rightarrow \partial N(M)$ of the normal disk bundle. Denote by M^+ the image of M under λ . In the following, we will only consider framed links.

Then, Fenn and Rourke associate to $L \subset Q$ an augmented rack, called the *fundamental rack* of the link L , which is the space Γ of homotopy classes of paths in $Q_0 := \text{closure}(Q \setminus N(L))$ of L , from a point in M^+ to some base point q_0 . During the homotopy, the final point of the path at q_0 is kept fixed and the initial point is allowed to wander at will on M^+ .

The set Γ has an action of the fundamental group $\pi_1(Q_0, q_0)$ defined as follows: let γ be a loop in Q_0 based at q_0 representing an element $g \in \pi_1(Q_0)$. If $\alpha \in \Gamma$ is represented by the path α , define $a \cdot g$ to be the class of the composite path $\alpha \circ \gamma$.

We can use this action to define a rack structure on Γ . Let $p \in M^+$ be a point on the framing image. Then p lies on a unique meridian circle of the normal disk bundle. Let m_p be the loop based at p which follows the meridian around in a positive direction. Let $a, b \in \Gamma$ be represented by paths α, β respectively. Let $\partial(b)$ be the element of $\pi_1(Q_0, q_0)$ determined by the homotopy class of the loop $\beta^{-1} \circ m_{\beta(0)} \circ \beta$. The *fundamental rack of the framed link L* is defined to be the set $\Gamma = \Gamma(L)$ with the operation

$$a \triangleleft b := a \cdot \partial(b) := [\alpha \circ \beta^{-1} \circ m_{\beta(0)} \circ \beta].$$

Fenn and Rourke show in [6] Proposition 3.1, p. 359, that Γ is indeed a rack, and go on to show that $\partial : \Gamma \rightarrow \pi_1(Q_0, q_0)$ is an augmented rack.

Let us now come to an "oidification" of their construction, i.e. the construction of a fundamental rackoid Φ on which the fundamental groupoid $\Pi(Q_0)$, i.e. the set of homotopy classes of paths in Q_0 from some point q_0 to some other point q_1 , acts naturally.

The main idea is to replace the set of homotopy classes Γ by the set $\Phi(Q_0)$ consisting of homotopy classes of paths α from some point $s(\alpha) = q_0 \in Q_0$ to a point in M^+ at $\frac{1}{2}$, and then back to some other point $t(\alpha) = q_1 \in Q_0$. There is a natural action of the fundamental groupoid $\Pi(Q_0)$ on $\Phi(Q_0)$ from the left resp. from the right induced by concatenation of paths. As before one has to rescale in order to keep the passage in M^+ at $t = \frac{1}{2}$.

There is also a natural map $\partial : \Phi(Q_0) \rightarrow \Pi(Q_0)$ where for $\alpha \in \Phi(Q_0)$ with $s(\alpha) = q_0$ and $t(\alpha) = q_1$, $\partial\alpha$ is given by the concatenation of the paths from q_0 to $\alpha(\frac{1}{2})$, the meridian at the point $\alpha(\frac{1}{2})$, and finally the paths from $\alpha(\frac{1}{2})$

to q_1 . In the same way as before using the non-unitary version of Theorem 2.14, this map gives rise to a non-unital augmented rackoid, which we call the *fundamental rackoid* of the link L .

7 Conclusion

Having established the basic properties of Lie rackoids, we are left with many open questions.

First of all, there is structure theory for Lie rackoids to be done (morphisms, weak morphisms, i.e. Morita equivalences, etc). The functoriality of the concept is a important feature for modern differential geometry.

Concerning Lie rack bundles, one may ask about the notion of principal R -bundles where R is a Lie rack. It should not be too difficult to find a suitable definition and to show that these are special cases of Lie rackoids. As for principal bundles, one would like to have Atiyah sequences for those.

One of the most important questions is certainly about the integration of Leibniz algebroids into Lie rackoids. For the moment, there are several constructions integrating finite-dimensional Leibniz algebras to Lie racks, but unfortunately not in a functorial way. One could try to integrate Leibniz algebroids along the lines of Mackenzie for transitive Leibniz algebroids, or right away along the lines of Crainic-Fernandes for arbitrary Leibniz algebroids, with probably some discreteness conditions coming into the game (for rendering the analogue of the Weinstein \mathcal{C}^0 -manifold a smooth manifold).

Lie rackoids seem to be the “integral manifolds” which correspond to some kind of non-commutative foliations (the Leibniz algebroid). Observe that we did not admit non-Hausdorff manifolds in our setting, excluding interesting examples from foliation theory. Even more fundamental, in the same way as étale Lie groupoids may be seen as generalized spaces (see [5]), étale Lie rackoids may be seen as generalized non-commutative spaces. The open problem is to make this relation precise in whatever non-commutative framework you prefer.

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